



University of Southern Queensland  
Faculty of Health, Engineering and Sciences

**Smart Composite Wind Turbine Blades  
- A Pilot Study**

A Dissertation Submitted by

Eris Elianddy Supeni, B.Eng.(Hons), M.Sc.(Mech. Eng.)

For the Award of

**Doctor of Philosophy**

2015

# Abstract

Wind energy is seen as a viable alternative energy option to meet future energy demands. The blades of wind turbines have been long recognised as the most critical component of the wind turbine system. The turbine blades interact with the wind flow to turn the wind turbine, in effect acting as a tool to extract the wind energy and turn it into electrical energy.

As the wind industry continues to explore new technologies, the turbine blade is a key aspect of better wind turbine designs. Harnessing greater wind power requires larger swept areas. Increasing the length of the turbine blades increases the swept area of a wind turbine, thereby improving the production of wind energy. However, longer turbine blades significantly add to the weight of the turbine, and they also suffer from larger bending deflections due to flapwise loads. The flapwise bending deflections not only result in a lower performance of electrical power generation but also increase in material degradation due to high fatigue loads and can significantly shorten the longevity for the turbine blade.

To overcome this excessive flapwise deflection, it is proposed that shape memory alloy (SMA) wires be used to return the turbine blade back to its optimal operational shape. The work presented here details the analytical and experimental work that was carried out to minimise blade flapping deflection using SMA.

This study proposes a way to overcome the wind blade deflection using shape memory alloy (SMA) wires. A finite element model has been developed for the

---

simulation of the deflection response of a horizontal axis wind turbine blade using an SMA wire arrangement. The model was developed on the commercial finite element ABAQUS<sup>®</sup>, and focused on design and analysis, to predict the structural response. Experimental work was carried out to investigate the feasibility of the model based on a plate-like structure. An Artificial Neural Network (ANN) was used to predict the performance of the smart wind turbine blades.

From this study, the model of a smart wind turbine, incorporating SMA wires, was determined to be capable of recovering from large deflections. The coefficient of performance of the smart wind turbine blade was also determined to be higher than the coefficient for a conventional turbine blade. The results showed that by increasing the number of SMA wires, the actuation provided is sufficient to recover from significant blade deflection resulting in a significant increase in the lift produced by the blade. It was determined that the coefficient of performance for turbine blades with SMA wires is 0.45 compared to 0.42 for turbine blades without SMA. These findings will be a significant achievement in the development of a smart wind turbine blade.

It is expected that the use of smart wind turbine blades, incorporating SMA in their design, will not only increase the power output of the wind turbine but also prolong the lifetime of the turbine blade itself through a reduction of the bending deflections.

# List of Publications Arising from this Study

Most of the discussion and results presented in the thesis are based on the following publications. Several passages in this thesis contain materials that have been copied verbatim, or with some adaptation, from thesis publications. All such copied materials were originally written by myself.

- (i) Supeni E.E., Epaarachchi J.A., Islam M.M. and Lau K.T., “Smart Structure for Small Wind Turbine Blades”, *The 4<sup>th</sup> International Conference on Smart Materials and Nanotechnology in Engineering (SMN2013)*, Hotel Grand Chancellor Surfer Paradise, Gold Coast, Queensland, Australia, Volume 8793, pp1–10, 10–12 July 2013, Society of Photo-Optical Instrumentation Engineers (SPIE) <http://dx.doi.org/10.1117/12.2027725>
- (ii) Supeni E.E., Epaarachchi J.A., Islam M.M. and Lau K.T., “Genetic Algorithm Based for Artificial Neural Network for Predicting the Deflection of Self-Straightening Wind Turbine Blade”, *The 3<sup>rd</sup> Malaysian Postgraduate Conference (MPC2013)* Sydney, New South Wales, Australia, MPC2013–27, pp233–242, 3–4 July 2013
- (iii) Supeni E.E., Epaarachchi J.A., Islam M.M. and Lau K.T., “Development of Smart Wind Turbine Blades”, *The 8<sup>th</sup> Asian-Australasian Conference on Composite Materials (AACM8)*, Petronas Kuala Lumpur Convention Centre,

- Malaysia (KLCC), Kuala Lumpur, Malaysia, pp199–205, 6–8 November 2012, <http://eprints.usq.edu.au/id/eprint/22295>
- (iv) Supeni E.E., Epaarachchi J.A., Islam M.M. and Lau K.T., “Design of Smart Structures for Wind Turbine Blades”, *The 2<sup>nd</sup> Malaysian Postgraduate Conference (MPC2012)*, Bond University, Gold Coast, Queensland, Australia, pp20–36, 7–9 July 2012 , <http://eprints.usq.edu.au/21673>
- (v) Supeni E.E., Epaarachchi J.A., Islam M.M. and Lau K.T., “Design and Analysis of a Smart Composite Beam for Small Wind Turbine Blade Construction”, *The Southern Region Engineering Conference (SREC)*, USQ, Toowoomba, Australia, 1 September 2012
- (vi) Supeni E.E., Epaarachchi J.A., Islam M.M. and Lau K.T., “Smart Structure Wind Blade”, *Fibre-Reinforced Composites Development and Applications in Renewable Energy Workshop* , Composites Australia, USQ Toowoomba, Queensland, Australia, 4 June 2012
- (vii) Supeni E.E., Epaarachchi J.A., Islam M.M. and Lau K.T., “Development of Smart Wind Turbine Blades”, *Engaged Research Evening Posters*, Toowoomba, Queensland, Australia, 26 April 2012
- (viii) Supeni E.E., Epaarachchi J.A., Islam M.M. and Lau K.T., “Development of Artificial Neural Network in Predicting Performance of the Smart Wind Turbine Blade”, *Journal of Mechanical Engineering and Sciences (JMES)*, ISSN (Print): 2289-4659; e-ISSN: 2231-8380; Volume 6, pp. 734-744, June 2014

# Certification of Dissertation

I certify that the ideas, designs and experimental work, results, analyses and conclusions set out in this dissertation are entirely my own effort, except where otherwise indicated and acknowledged. The work is original and has not been previously submitted for assessment in any other course or institution, except where specifically stated.

ERIS ELIANDDY SUPENI, B.ENG.(HONS), M.SC.(MECH. ENG.)

W0106520

---

Signature of Candidate

Date

## ENDORSEMENT

Supervisory Team

---

Dr. Jayantha A. Epaarachchi

Signature of Principal Supervisor

Date

---

Dr. Md. Mainul Islam

Signature of Associate Supervisor

Date

---

Prof. Dr. Alan Kin-tak Lau

Signature of Associate Supervisor

Date

# Acknowledgments

I would like to thank Dr. Jayantha Epaarachchi, who served as a supervisor of my thesis committee and as my advisor for the last three years. He has been there for me through thick and thin; we have had long conversations about school and research. I consider him a great advisor, an excellent mentor, and a caring friend. I also want to thank Dr. Md. Mainul Islam and Prof. Alan Kin-tak Lau for serving on my committee and for offering their knowledge through meetings and words of encouragement throughout my time at USQ. I thank my fellow Dr. Gayan, Dr. Hafizi, Dr. Muhamad, Dr. Zamir, Wayne, Martin, Dr. Salahudin, Anthony and CEEFC USQ Australia members for their support, and last but not least the Malaysian Government Scholarships. Not forgotten, thank God Almighty, who has given me strength and energy for my daily life. Special thanks also go to my parents, Supeni, Norhanah, late Mohd Yusoff and Mariam, who have always praised me when I was doing well and offered support and motivation when I was down. I must also thank my wife, Yusmaria, for always standing by my side and keeping me focused during times of stress and distraction. My children Nazmeen, Nazim and Nuha, who provided me with unconditional advice and love. Finally, I wish to thank a group of people whom I never met, but I have widely used their products, the ABAQUS/CAE team, MATLAB team, L<sup>A</sup>T<sub>E</sub>X group, WinEdt, TeXstudio, among others, who provide free-open source software package to the community.

ERIS ELIANDDY SUPENI, B.ENG.(HONS), M.SC.(MECH. ENG.)

*University of Southern Queensland*

*22 July 2015*

# Contents

<b>Abstract</b>	<b>i</b>
<b>List of Publications Arising from this Study</b>	<b>iii</b>
<b>Acknowledgments</b>	<b>vi</b>
<b>List of Figures</b>	<b>xv</b>
<b>List of Tables</b>	<b>xxv</b>
<b>Notation</b>	<b>xxvii</b>
<b>Acronyms &amp; Abbreviations</b>	<b>xxix</b>
<b>Chapter 1 Introduction</b>	<b>1</b>
1.1 Background and Significance . . . . .	3
1.2 Problem Statement . . . . .	4
1.3 Objectives of the Project . . . . .	6



## CONTENTS

viii

---

1.4	Research Gap and Innovation . . . . .	7
1.5	Organisation of the Thesis . . . . .	9
<b>Chapter 2 Literature Review</b>		<b>11</b>
2.1	Introduction . . . . .	11
2.1.1	History of Wind Turbines . . . . .	11
2.2	Wind Turbine Blade Geometry . . . . .	15
2.3	Modern Wind Turbines . . . . .	20
2.4	Identification of Parameters for Efficiency Improvements . . . . .	22
2.5	Smart Materials . . . . .	25
2.6	Shape Memory Alloy (SMA) . . . . .	26
2.7	Characterisation of SMA for Smart Wind Turbine Blades . . . . .	33
2.7.1	Shape Memory Alloy Behaviour . . . . .	35
2.7.2	Superelastic Behaviour of SMA . . . . .	35
2.7.3	Macroscopic Behaviours of SMA . . . . .	37
2.7.4	Microscopic Behaviours of SMA . . . . .	41
2.7.5	Factors Affecting the Effectiveness of SMA . . . . .	42
2.8	Design of General Mechanism for a Wind Turbine Blades with SMA	45
2.9	Proposed Use of SMA . . . . .	48

---

2.10 Analysis of the Structural Performance of Wind Turbine Blades . . . . .	48
2.10.1 Aerodynamics . . . . .	48
2.10.2 The Blade Element Theory (BET) . . . . .	54
2.10.3 The Actuator Disk Theory . . . . .	56
2.10.4 The Panel Code Method . . . . .	61
2.11 Design Analysis . . . . .	64
2.12 Wind Turbine Blade Fatigue Loads . . . . .	69
2.13 Structural Analysis of a Wind Turbine Blade . . . . .	71
2.13.1 Considering the Blade as a Structural Beam . . . . .	71
2.13.2 Gravitational and Centrifugal Loads . . . . .	74
2.13.3 Internal Beam Structure . . . . .	76
2.13.4 Laminate Configuration . . . . .	77
2.13.5 Wind Turbine Blade's Shell . . . . .	80
2.13.6 Wind Turbine Blade Root Design . . . . .	81
2.13.7 Stiffness of Wind Turbine Blade . . . . .	82
2.14 Performance Analysis . . . . .	83
2.15 Wind Turbine Blade Structure . . . . .	86
2.16 Recovery of Wind Blade Deflection . . . . .	87
2.17 Proposed Conceptual Model . . . . .	89

**CONTENTS** **x**

---

2.18 Summary of Literature Review . . . . . 92

**Chapter 3 FEA Model and ANN Model Development** **93**

3.1 Introduction . . . . . 93

3.2 Finite Element Model Development . . . . . 94

3.2.1 FEA Modelling . . . . . 96

3.2.2 Preliminary Study of a Graded Plate . . . . . 99

3.3 Types of Elements . . . . . 100

3.3.1 Continuum Shell Elements (SC8R) . . . . . 100

3.3.2 Conventional Shell Elements (S4R) . . . . . 101

3.3.3 Truss Element (T3D2) . . . . . 101

3.4 Types of Interactions and Boundary Conditions . . . . . 102

3.4.1 Constraint 1 . . . . . 102

3.4.2 Constraint 2 . . . . . 103

3.4.3 Modelling Discretisation . . . . . 103

3.4.4 Creating Composite Layup and Defining Material Properties 104

3.4.5 Creating SMA and Defining Properties . . . . . 105

3.5 ANN Model Development . . . . . 107

3.6 Performance Criteria . . . . . 113

<b>CONTENTS</b>	<b>xi</b>
3.6.1 Multi-Back Propagation (MBP) . . . . .	114
3.6.2 Non-Linear Auto-Regressive with Exogenous (NARX) Input . . . . .	114
3.7 Summary of FEA Model and ANN Development . . . . .	116
<b>Chapter 4 Experimental Setup</b>	<b>117</b>
4.1 Introduction . . . . .	117
4.2 Specimen Fabrication . . . . .	117
4.2.1 Preparation of the Epoxy Resin . . . . .	119
4.3 Investigation of SMA Wires Transition Using DSC . . . . .	119
4.4 Calibration of SMA Wires Attached to a Plate-Like Structure . .	123
4.5 Deflection Test for a GFRP Plate . . . . .	124
4.6 Experimental Setup Arrangement . . . . .	124
4.7 Summary of the Experimental Setup . . . . .	128
<b>Chapter 5 Results and Discussion</b>	<b>130</b>
5.1 Introduction . . . . .	130
5.2 Characterisation of the GFRP . . . . .	130
5.3 Thermo-Mechanical Behaviour of an SMA Wire . . . . .	132
5.4 Calibration of an SMA Wire . . . . .	133

---

5.5	Deflection Test . . . . .	136
5.6	Deflection of the Graded Beam . . . . .	137
5.7	Tuning FEA for Large Deflection of the Model . . . . .	140
5.8	Tuning-Up ANN . . . . .	142
5.9	Prediction of ANN . . . . .	143
5.10	Development of ANN 1 . . . . .	144
5.10.1	Predicting the Number of SMA Wires (NW) using Load (L), Current (I) and Deflection (d) as the Input Vector . .	144
5.11	Development of ANN 2 . . . . .	150
5.11.1	Predicting Current (I) using Load (L), the Number of SMA Wires (NW) and Deflection (d) as the Input Vector . . . .	150
5.12	Development of ANN 3 . . . . .	154
5.12.1	Predicting Deflection using Load (L), the Number of SMA Wires (NW) and Current (I) as the Input Vector . . . . .	154
5.13	Implementing Robustness Testing . . . . .	158
5.14	Specification of Specimen . . . . .	159
5.15	Preliminary Study: Use of the SMA Mechanism . . . . .	160
5.15.1	Embedded SMA Wires . . . . .	160
5.15.2	Suspended SMA Wires . . . . .	166

<b>CONTENTS</b>	<b>xiii</b>
5.16 Deflection and Load Relationship . . . . .	172
5.17 SMA Wires Arrangement . . . . .	175
5.18 Results of Parametric Studies . . . . .	175
5.18.1 Effect of Anchoring Heights in 300 mm plate . . . . .	175
5.18.2 Effect of the Number of SMA Wires in the 300 mm plate .	179
5.18.3 Effect of Heat Sleeving . . . . .	181
5.18.4 Smart Wind Blade Deflection for Stress Recovery . . . . .	183
5.18.5 Stress Recovery of SMA Wires in 1000 mm plate . . . . .	183
5.18.6 Effect of the Number of SMA Wires for Stress Recovery . . . . .	186
5.19 Comparison of Power Performance . . . . .	188
5.20 Summary of the Results . . . . .	191
 <b>Chapter 6 Conclusions and Further Work</b>	 <b>193</b>
6.1 Conclusions . . . . .	193
6.2 Limitations of the Study . . . . .	195
6.3 Further Work . . . . .	196
 <b>References</b>	 <b>198</b>
 <b>Appendix A Mechanical Properties of Specimens of SMA</b>	 <b>212</b>

<b>CONTENTS</b>	<b>xiv</b>
<b>Appendix B Mechanical Specification of GFRP Specimens</b>	<b>225</b>
<b>Appendix C Test Rig Design</b>	<b>235</b>
<b>Appendix D DC Power 1 Supply Unit</b>	<b>238</b>
<b>Appendix E DC Power 2 Supply Unit</b>	<b>240</b>
<b>Appendix F Kinetix Laminating/R240 High Performance</b>	<b>242</b>
<b>Appendix G Data for ANN</b>	<b>245</b>
<b>Appendix H Dynalloy Inc. Invoice &amp; Test Rig Approval</b>	<b>250</b>
<b>Appendix I Performance Coefficient M-File</b>	<b>253</b>
<b>Appendix J Tip deflection against current at various load at 40, 50 and 60 mm</b>	<b>256</b>
<b>Appendix K Effect of Heat Sleeving</b>	<b>260</b>
<b>Appendix L Script M-file for ANN 1, ANN 2 and ANN 3</b>	<b>262</b>
<b>Appendix M Running ANN Model Simulation</b>	<b>268</b>

# List of Figures

1.1	Australian Renewable Energy Target: 20 % by 2020 (ACEC 2012 <i>b</i> )	2
1.2	Renewable capacity installed since 2001 (ACEC 2012 <i>a</i> ) . . . . .	2
1.3	Innovative approach of the smart structure in a wind turbine blade	10
2.1	Types of wind turbine - from left, Savonius, Darrieus and H-Rotor (Sandra et al. 2008) . . . . .	14
2.2	Flatback development . . . . .	16
2.3	Controlling smart blades using piezoelectric . . . . .	17
2.4	Smart blade concept (Bak et al. 2007) . . . . .	19
2.5	Bend-twist coupling, aileron, changing shape and microtab (Barlas & Kuik 2007) . . . . .	20
2.6	Various types of mechanism for smart materials (Leo 2007) . . . . .	25
2.7	Example SMA application in Variable Geometry Chevron (VGC) for Boeing 777 (Hartl & Lagoudas 2007) . . . . .	30
2.8	Application of SMAs to an automatic oil-level-adjustment device for the Shinkansen bullet train (Otsuka & Kakeshita 2002) . . . . .	31



---

2.9	Corvette’s heat-activated smart material (Auto 2013) . . . . .	32
2.10	Actuation stress-strain of selected SMA (Lagoudas 2008) . . . . .	34
2.11	Actuation frequency diagram of different active materials (Lagoudas 2008) . . . . .	34
2.12	(a) Stress-strain curve of SME and (b) SE . . . . .	36
2.13	General SMA mechanism . . . . .	37
2.14	Phase diagram of a NiTi alloy in which the phase equilibrium is between 49.5–57 % nickel by atomic weight percentage (Otsuka & Ren 2005) . . . . .	38
2.15	SMA stress-strain (Otsuka & Ren 2005) . . . . .	39
2.16	Martensite crystal structure (Volk & Lagoudas 2005) . . . . .	41
2.17	Austenite lattice crystalline structure . . . . .	42
2.18	Schematic mechanism diagram of SMA actuators combined with a spring (Sun et al. 2012) . . . . .	47
2.19	Major systems and components of a horizontal-axis wind turbine (EWEA 2006) . . . . .	50
2.20	Thick airfoil shape of A1 series family (Dahl et al. 1999) . . . . .	52
2.21	Diagram of a wind turbine blade sectioned into individual blade elements. The rotor angular velocity is $\Omega$ ; $r$ is the radius of the section, $dr$ is the differential section thickness, and $c$ is the section chord length. The lift, $F_L$ and drag, $F_D$ forces are found for every airfoil section (Eggleston & Stoddard 1987) . . . . .	54

---

2.22	Apparent flow velocity at radius $r$ (Eggleston & Stoddard 1987) . . . . .	55
2.23	The energy extracting stream-tube of a wind turbine (Burton et al. 2011) . . . . .	56
2.24	Wind turbine illustration: actuator disk model; $U$ , mean velocity; 1, 2, 3 and 4 indicate locations (Eggleston & Stoddard 1987) . . . . .	57
2.25	Panelling code direction (Hess & Year 1990) . . . . .	62
2.26	Airfoil replaced by $N$ line vortices (Hess & Year 1990) . . . . .	63
2.27	Typical cross section of wind turbine blade (Sorensen et al. 2004) . . . . .	64
2.28	Girder box showing laminate, sandwich, adhesive bonds (Sorensen et al. 2004) . . . . .	65
2.29	Direction of laminates (Sorensen et al. 2004) . . . . .	65
2.30	Airfoil characteristics wind turbine (Pozrikidis 2009) . . . . .	66
2.31	Design parameters (Eggleston & Stoddard 1987) . . . . .	67
2.32	Optimum tip speed ratios for wind turbine systems (Hau 2006) . . . . .	68
2.33	Wind turbine loading regime (Sutherland 1996) . . . . .	69
2.34	Typical wind turbine blade cross-section (Sorensen et al. 2004) . . . . .	70
2.35	Bending moment and shear force against radius in a large turbine blade (Burton et al. 2001) . . . . .	72
2.36	Blade load (sketch view) (Peter & Richard 2012) . . . . .	73
2.37	Inertial forces acting on a wind turbine blade (schematic view) (Eapaarachchi 2002) . . . . .	73

---

2.38	Bending moment against radius in a large turbine blade (Nolet 2011)	74
2.39	Internal structure described in I-beam (Burton et al. 2011)	76
2.40	Shearing and reinforcement of a simple frame concept (Burton et al. 2011)	78
2.41	Extended framework with shear reinforcement (Burton et al. 2011)	79
2.42	Blade bending phenomenon (Burton et al. 2011)	83
2.43	Power coefficient curves for the three different wind turbine types (Sandra et al. 2008)	84
2.44	Growth of commercial wind technology (EWEA 2009)	85
2.45	Example of ply drop off in composite materials (Trethewey et al. 1990)	86
2.46	Material specimen preparation (Cairns et al. 1997)	87
2.47	Illustration of the structural model of a three-bladed free body diagram (Larsen et al. 2004)	88
2.48	Illustration of pitch moment contributions from blade loads in the deflected location (Larsen et al. 2004)	88
2.49	Modern wind turbine blade assembly (Petersen & Davis 2011)	90
2.50	Conceptual design of plate-like structure (Petersen & Davis 2011)	91
2.51	A cross section of a GFRP blade. The blade stretched over a composite frame (light grey) and central spar (yellow and green) (Petersen & Davis 2011)	91
3.1	Schematic diagram of the model (side view)	98

---

3.2	Suspended SMA of 1 wire and the GFRP which have undergone a meshing process . . . . .	98
3.3	Graphical model representation with plies configuration orientation	101
3.4	Differences between conventional and continuum shell elements (Simulia 2012) . . . . .	102
3.5	MPC implemented between the SMA wires and the GFRP plate (end section view) . . . . .	104
3.6	Sketching part of the plate . . . . .	105
3.7	Sketching part of the wire . . . . .	106
3.8	The orientation of the angle between the SMA wire and the GFRP plate in the side view angle . . . . .	106
3.9	Biological diagram of a neuron . . . . .	108
3.10	Artificial neuron diagram . . . . .	111
3.11	Graphical representation of the MBP network . . . . .	114
3.12	Graphical representation of NARX network . . . . .	115
4.1	Photograph of specimen preparation . . . . .	118
4.2	Photograph of DSC test equipment and the SMA specimen used .	121
4.3	DSC curve for 0.50 mm diameter NiTi . . . . .	122
4.4	Photograph of the calibration setup for SMA . . . . .	123
4.5	Experimental setup arrangement with the test rig . . . . .	125

## LIST OF FIGURES

xx

---

4.6	Schematic operating principle . . . . .	126
4.7	Schematic diagram of SMA wires arrangement . . . . .	126
4.8	Photograph of experimental setup and values reading of the power supply in series mode driven when is current is activated (insert picture) . . . . .	127
4.9	Photograph of the tip deflection (a) before heating (b) after heating (section view) . . . . .	127
4.10	Schematic diagram of the experimental setup . . . . .	128
5.1	Tensile test setup with measurement of longitudinal and transverse strains by a contact extensometer . . . . .	131
5.2	Stress-strain response as a function of temperature for the SMA wire. All tests were performed on as-received. . . . .	132
5.3	Calibration test curve . . . . .	133
5.4	Calibration test and heat sleeve/non-heat sleeve test . . . . .	134
5.5	Load test of 0.5 mm SMA between relaxation and contraction . . . . .	135
5.6	Load-deflection curves for Flexinol 90 . . . . .	136
5.7	Graphical model representation with part of the assembly layout . . . . .	137
5.8	Graded beam specimen representing plies drop off imitation . . . . .	137
5.9	Graphical model representation with number of plies configuration (top view) . . . . .	138
5.10	Deflection pattern profile for the whole graded beam . . . . .	139

---

5.11 Comparison of vertical deflection of GFRP (with EPS/without EPS) between FEA and experiment . . . . .	139
5.12 Deflection contour S4R of the GFRP plate . . . . .	140
5.13 Deflection contour of SC8R of the GFRP plate . . . . .	141
5.14 Schematic diagram representation for model ANN 1 . . . . .	144
5.15 Example of NARX network with 10 hidden layers and 2 delay time by MATLAB . . . . .	145
5.16 Example of MBP diagram network with 50-40 hidden layers . . . . .	145
5.17 Best performance curve for ANN 1 . . . . .	146
5.18 The networks performance for ANN 1 . . . . .	147
5.19 Error histogram of the NARX prediction model for ANN 1 . . . . .	148
5.20 Response of NARX model for output deflection for ANN 1 by MATLAB® . . . . .	149
5.21 The deflection output and network output for ANN 1 by MBP . . . . .	149
5.22 Schematic diagram for model ANN 2 . . . . .	150
5.23 Best performance curve for ANN 2 . . . . .	151
5.24 Error histogram of the NARX prediction model for ANN 2 . . . . .	152
5.25 The networks performance for ANN 2 . . . . .	153
5.26 NARX prediction model for performance for ANN 2 . . . . .	153
5.27 Schematic diagram for model ANN 3 . . . . .	154

---

5.28	Best performance curve for ANN 3 . . . . .	155
5.29	Error histogram of the NARX prediction model for ANN 3 . . . . .	156
5.30	The regression analysis for ANN 3 . . . . .	157
5.31	Response of the NARX prediction model for performance for ANN 3	158
5.32	Schematic ply configuration of the actual blade . . . . .	159
5.33	Embedded SMA fabrication . . . . .	160
5.34	Schematic diagram of embeded SMA wires . . . . .	162
5.35	Photograph preliminary study setup for embedded SMA and sus- pended SMA . . . . .	163
5.36	Heating and cooling curves of the SMA mechanism design . . . . .	164
5.37	Photograph of the specimen embedded SMA wires fabrication . . . . .	165
5.38	Photograph showing that delamination occurred along the embed- ded SMA wires . . . . .	166
5.39	Photograph of preliminary suspended SMA wires . . . . .	167
5.40	Comparison of suspended SMA wires under deflection testing with different numbers of SMA wires at specific heights . . . . .	168
5.41	Response time of suspended wire . . . . .	169
5.42	Tips deflection with different number of SMA wires under variable load at specific height . . . . .	170
5.43	Current and voltage curves at specific height . . . . .	171

---

5.44 Simulation of smart wind blade model . . . . .	173
5.45 Calibration of the smart wind blade model under deflection . . . . .	174
5.46 Tip deflection against current at different anchoring heights . . . . .	176
5.47 Tip deflection against current at various load at 30 mm height, respectively . . . . .	178
5.48 Tip deflection against current at different number of SMA Wires . . . . .	180
5.49 Effect of heat sleeving and without heat sleeving at s1=366.8 g, s2=460.1 g, s3=576.8 g, s4=716.3 g and s5=1016.7 g for 2 SMA wire	182
5.50 Deflection and alleviation response of the smart blade . . . . .	183
5.51 Simulation of the smart blade under deformation and stress recovery	184
5.52 Stress of the blade under deflection for 1000 mm . . . . .	185
5.53 Strain under deflection - the blade under deflection for 1000 mm . . . . .	186
5.54 Voltage and current curve for 1000 mm specimen . . . . .	187
5.55 Deflection curve for 1000 mm specimen . . . . .	187
5.56 Voltage and current curve for 1000 mm specimen . . . . .	188
5.57 $C_p$ - $\lambda$ performance curve for a modern three-blade turbine . . . . .	191
J.1 Tip deflection against current at various load at 40 mm height, respectively . . . . .	257
J.2 Tip deflection against current at various load at 50 mm height, respectively . . . . .	258



---

J.3 Tip deflection against current at various load at 60 mm height,  
respectively. . . . . 259

K.1 Effect of heat sleeving and without heat sleeving at s1=366.8 g,  
s2=460.1 g, s3=576.8 g, s4=716.3 g and s5=1016.7 g for 6 SMA wire260

K.2 Effect of heat sleeving and without heat sleeving at s1=366.8 g,  
s2=460.1 g, s3=576.8 g, s4=716.3 g and s5=1016.7 g for 4 SMA wire261

# List of Tables

2.1	Summarise of modern and historical wind turbine designs (Peter & Richard 2012) . . . . .	24
2.2	Analysis methods of HAWT performance . . . . .	53
2.3	Theoretical Annual Specific Yield of HAWTs and VAWTs (Malcolm 2003) . . . . .	85
3.1	Laminate configurations . . . . .	99
3.2	Mechanical properties of SMA, GFRP, Epoxy and Core . . . . .	100
4.1	Transformation temperature of SMA . . . . .	122
5.1	Four parts of graded beam assembly . . . . .	131
5.2	Comparison of FEA and experimental work without SMA for validation . . . . .	141
5.3	Prediction of the deflection with respect to the number of SMA wires using various models . . . . .	146
5.4	The results of the NARX model training for ANN 1 . . . . .	147

---

5.5	The results of the NARX model training for ANN 2 . . . . .	151
5.6	The results of the NARX model training for ANN 3 . . . . .	155
5.7	Plies configuration of the plate . . . . .	159
5.8	Gradient response for suspended wire . . . . .	172
5.9	Deflection $d$ , reading values for 6 SMA wires at 1000 mm, 60 mm anchoring height . . . . .	184
5.10	Optimised values of the curve equations presented in Equation 5.5 (Slootweg et al. 2003) . . . . .	190
B.1	Tensile test for part 1 : 4 plies . . . . .	226
B.2	Tensile test for part 2 : 8 plies . . . . .	226
B.3	Tensile test for part 3 : 12 plies . . . . .	226

# Notation

$\alpha$	angle of attack, $^{\circ}$
$\theta$	angle of twist, $^{\circ}$
$\nu$	Poisson ratio
$\sigma$	stress, Pa
$\Gamma$	vortex strength
$W_A$	resultant velocity, $ms^{-1}$
$r$	radius of the blade section considered, m
$\Omega$	rotational speed of the turbine, $rads^{-1}$
$U_0$	velocity of the wind at tip, $ms^{-1}$
$\lambda$	tip speed ratio
$\rho$	density of air, $kgm^{-3}$
$C_p$	coefficient of power
$\Delta A$	small portion area of a wind turbine blade
$L_A$	lift force, N
$V$	wind velocity, $ms^{-1}$
<i>at.wt.</i>	atomic weight
$A_s$	austenite start, $^{\circ}C$
$A_f$	austenite finish, $^{\circ}C$

---

$M_s$	martensite start, °C
$M_f$	martensite finish, °C
$Ac_{\text{func.}}$	active functional
$\varepsilon_m^y$	martensite twin strain
$\varepsilon_m^d$	martensite detwin strain
$\varepsilon_m^y$	martensite twin strain
$\varepsilon_m^d$	martensite detwin strain
$E$	Young's Modulus, MPa
$E_{m,t}$	Young's Modulus twin, MPa
$E_{m,d}$	Young's Modulus detwin, MPa
$\Delta$	percentage difference, %
$W$	width, mm
$D$	depth, mm
$H$	height, mm
$NW$	number of SMA wires
$L$	applied load, N
$I$	applied current, Amp
$N$	line of vortices
$d$	deflection, mm
$V$	voltage, V
$w$	power, W
$P_{wt}$	power extracted from the wind, kW

# Acronyms and Abbreviations

ANN	artificial neural network
AuCd	Aurum Cadmium
AuCu	Aurum Copper
BET	Blade Element Theory
CAD	computer aided design
CAE	computer aided engineering
CEEFC	Centre of Excellence Engineered in Fibre Composite
CuZn	Copper Zinc
EPS	expanded polystyrene
EWEA	European Wind Energy Association
FEA	finite element analysis
GFRP	glass fibre-reinforced polymer
GUI	graphical user interface
HAWT	horizontal axis wind turbine
IGES	initial graphics exchange specification
LM	Lavenberg-Marquardt
LVDT	linear variable differential transformer
MATLAB	Matrix Laboratory
MBP	multi-back propagation
ML	machine learning

---

MLP	multi-layer perceptron
MSE	mean square error
NARX	Non-linear autoregressive with Exogenous
NiTi	Nickel Titanium
NACA	National Advisory Committee for Aeronautics
Nitinol	Nickel Titanium Ordnance Laboratory
NREL	National Renewable Energy Laboratory
N/A	not applicable
PPE	personal protective equipment
PVC	Polyvinyl Chloride
R	correlation coefficient factor
SMA	shape memory alloy
SME	shape memory effect
SE	superelasticity
TSR	tip speed ratio
USQ	University of Southern Queensland
UPM	Universiti Putra Malaysia
UD	unidirectional
VAWT	vertical axis wind turbine